

1.7 Linear Independence

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"We've begun to notice a deep connection between the behavior of the solutions of $A\vec{x} = \vec{b}$ and the reduced column form of A : e.g. - if all rows of A have pivots, the columns of A span \mathbb{R}^m and this equation is solvable for all \vec{b} .

or - if all columns of A have pivots, the homogeneous equation $A\vec{x} = \vec{0}$ has only the trivial solution and $A\vec{x} = \vec{b}$ has exactly one solution, if any.

The idea of having enough of the right vectors to solve any system will appear later in the notion of **basis** and will connect these two ideas (e.g., pivots in all rows and all columns of A), for now we give a definition to generalize the second case (A has pivots in each column.)"

Def: A set of vectors $\{\vec{v}_1, \dots, \vec{v}_p\}$ in \mathbb{R}^n is said to be **linearly independent** if the vector equation

$$x_1\vec{v}_1 + x_2\vec{v}_2 + \dots + x_p\vec{v}_p = \vec{0}$$

has only the trivial solution (i.e. $[\vec{v}_1 \dots \vec{v}_p]\vec{x} = \vec{0}$ has only the trivial sol'n).

If there are c_1, \dots, c_p , not all 0, s.t. $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_p\vec{v}_p = \vec{0}$ In this case, we call this

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_p\vec{v}_p = \vec{0} \leftarrow \text{equation a linear dependence}$$

we say $\{\vec{v}_1, \dots, \vec{v}_p\}$ is **linearly dependent**. relation for $\vec{v}_1, \dots, \vec{v}_p$

Ex1 Determine if $\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$, and $\vec{v}_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$ are linearly independent. **Nope**

To determine this, need see if there are nontrivial $x_1, x_2, x_3 \neq 0$.

$$x_1\vec{v}_1 + x_2\vec{v}_2 + x_3\vec{v}_3 = \vec{0}$$

$$x_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 2 \\ 2 & 5 & 1 \\ 3 & 6 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{bmatrix}$$

so we row reduce
 $[\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3 \ \vec{0}]$

$$\sim \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 \begin{bmatrix} 4 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 5 \\ 6 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \text{so we row reduce} \quad \sim \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Notice x_3 is free, so there is a nontrivial solution: $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ are linearly dependent. Specifically if $x_3 = 1 \Rightarrow x_1 = 2, x_2 = -1$ and $2\vec{v}_1 - \vec{v}_2 + \vec{v}_3 = \vec{0}$. ✓

Ex (Determine if the columns of $A = \begin{bmatrix} 0 & 1 & 4 \\ 1 & 2 & -1 \\ 5 & 8 & 0 \end{bmatrix}$ are linearly independent.

Similar

$$\begin{bmatrix} 0 & 1 & 4 & 0 \\ 1 & 2 & -1 & 0 \\ 5 & 8 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 13 & 0 \end{bmatrix} \quad \text{so yes, only trivial solution} \Rightarrow \begin{matrix} x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 = \vec{0} \\ \text{iff} \\ x_1 = x_2 = x_3 = 0. \end{matrix}$$

↳ no free variables

Geometry of linear independence

Notice! A set of vectors $\vec{v}_1, \dots, \vec{v}_p$ is linearly dependent if:

- for some $i, \vec{v}_i = \vec{0}$. or
- for some $j, \vec{v}_j \neq \vec{0}$ but is a linear combination of the preceding vectors $\vec{v}_1, \dots, \vec{v}_{j-1}$.

Why? Notice if $\vec{v}_1, \dots, \vec{v}_{p-1}$ all not $\vec{0}$ but $\vec{v}_p = \vec{0}$ then

$$c_1 = c_2 = \dots = c_{p-1} = 0 \quad \Rightarrow \quad c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_p \vec{v}_p = 0\vec{v}_1 + 0\vec{v}_2 + \dots + 0\vec{v}_p = 0 \cdot \vec{0} = \vec{0} \quad \rightarrow \text{linear dependence relation}$$

$c_p \neq 0$

not all zero. ✓

For the second case, if $\vec{v}_j \neq \vec{0}$ is a linear combination of $\vec{v}_1, \dots, \vec{v}_{j-1}$ then there are

$$\tilde{c}_1, \dots, \tilde{c}_{j-1} \quad (\text{not all zero, why?}) \quad \text{s.t.} \quad c_1 \vec{v}_1 + \dots + c_{j-1} \vec{v}_{j-1} = \vec{v}_j$$

$$\Rightarrow \quad c_1 \vec{v}_1 + \dots + c_{j-1} \vec{v}_{j-1} - \vec{v}_j = \vec{0}$$

$$\text{So} \quad c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_{j-1} \vec{v}_{j-1} + (-1) \vec{v}_j + 0 \vec{v}_{j+1} + \dots + 0 \vec{v}_{p-1} + 0 \vec{v}_p = \vec{0}$$

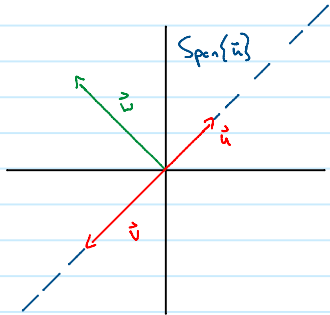
$\downarrow \quad \downarrow \quad \downarrow \quad \downarrow$
 $c_1 \quad c_2 \quad c_{j-1} \quad c_j$

is a linear dependence relation for $\vec{v}_1, \dots, \vec{v}_p$ (c_1, \dots, c_p not all zero).

"Okay, so if the zero vector is in the collection it's automatically linearly dependent, otherwise, it's dependent iff one of the vectors is a linear combination of the others, this yields a geometric understanding of linear dependence (and therefore linear independence)."

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Ex Two vectors are linearly dependent if they are scalar multiples of one another: let $\vec{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} -2 \\ -2 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$.

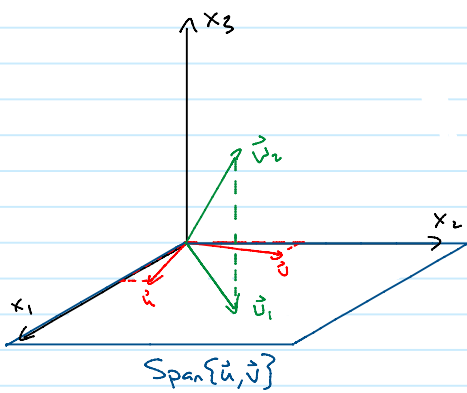


$$-2\vec{v} = \vec{u} \Rightarrow \vec{u} - 2\vec{v} = \vec{0} \text{ is a lin. dep. relation}$$

Notice \vec{w} is not a scalar multiple of either vector so

$\{\vec{u}\}$, $\{\vec{v}\}$, $\{\vec{w}\}$, $\{\vec{u}, \vec{w}\}$, $\{\vec{v}, \vec{w}\}$ are linearly independent
 $\{\vec{u}, \vec{v}\}$, $\{\vec{u}, \vec{v}, \vec{w}\}$ are linearly dependent.

Ex Let $\vec{u} = \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 1 \\ 4 \\ 0 \end{bmatrix}$. Then $\{\vec{u}, \vec{v}\}$ is linearly independent.
 ($\vec{u} \notin \text{Span}\{\vec{v}\}$ and $\vec{v} \notin \text{Span}\{\vec{u}\}$)



Note: for any \vec{w} , $\{\vec{u}, \vec{v}, \vec{w}\}$ is linearly independent so long as \vec{w} is not a linear combination of \vec{u} and \vec{v} i.e. if $\vec{w} \notin \text{Span}\{\vec{u}, \vec{v}\}$.

$\{\vec{u}, \vec{v}, \vec{w}_1\}$ is linearly dependent.

$\{\vec{u}, \vec{v}, \vec{w}_2\}$ is linearly independent.

"One final fact, linear independence relies on a homogeneous equation having only the trivial solution: from this we see"

Fact: If the collection $\{\vec{v}_1, \dots, \vec{v}_p\}$ of vectors in \mathbb{R}^n has more vectors than the number of entries in each vector ($p > n$) then $\{\vec{v}_1, \dots, \vec{v}_p\}$ is linearly dependent.

Why? $\begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_p \end{bmatrix} \vec{x} = \vec{0}$ has a nontrivial solution if there is a

free variable: $\begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_p \end{bmatrix} = \underbrace{\begin{bmatrix} - & - & - & - & - & - \\ - & - & - & - & - & - \end{bmatrix}}_P \Big\} n$

this matrix can only have three pivots, but has many more

this matrix can only have three pivots, but has many more columns. For go, some variable in the corresponding homogeneous system is free, and thus there is a nontrivial solution which in turn yields a linear dependence relation among the vectors $\vec{v}_1, \dots, \vec{v}_p$.